

A Transient Unified Model of Arc Weld Pool Couplings during Spot GTA Welding

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Introduction

Gas Tungsten Arc Welding – Tungsten Inert Gas



A highly coupled multiphysics problem





State of art – Towards a unified formulation





Toward a unified model

Mathematical formulation

Inside the cathode, plasma, and anode

$$\begin{aligned}
\nabla \cdot \left(\sigma \nabla V + \sigma \frac{\partial \vec{A}}{\partial t}\right) &= 0 \\
\sigma \frac{\partial \vec{A}}{\partial t} + \nabla \times \left(\frac{1}{\mu_0} \nabla \times \vec{A}\right) + \sigma \nabla V &= \vec{0}
\end{aligned}$$

$$\begin{aligned}
\nabla \cdot \vec{v} &= 0 \\
\rho \left(\frac{\partial \vec{v}}{\partial t} + \vec{v} \cdot \nabla \vec{v}\right) &= -\nabla p + \mu \nabla \cdot (\nabla \vec{v} + t \nabla \vec{v}) \\
+ \vec{j} \times \vec{B} + \rho_0 \vec{g} + w_p \rho_0 \beta (T - T_{ref}) \vec{g} \\
\rho C_p^{eq} \left(\frac{\partial T}{\partial t} + \vec{v} \cdot \nabla T\right) &= \nabla \cdot (\lambda \nabla T) + \vec{j} \cdot \vec{E} \\
+ \frac{5k_B}{2e} \vec{j} \cdot \nabla T - (1 - w_p) \cdot 4\pi\epsilon_N
\end{aligned}$$

$$\begin{aligned}
P_a - \lambda - \rho g \varphi &= -\gamma \frac{r \varphi_{rr} + \varphi_r (1 + \varphi_r^2)}{r(1 + \varphi_r^2)^{\frac{3}{2}}} \\
\lambda + \rho g(L + \psi) &= -\gamma \frac{r \psi_{rr} + \psi_r (1 + \psi_r^2)}{r(1 + \psi_r^2)^{\frac{3}{2}}}
\end{aligned}$$

$$\begin{aligned}
\text{Main boundary conditions} \\
\text{Plasma-cathode interface} \\
[-k \nabla T \cdot (-\vec{n})]_{anode} - [-k \nabla T \cdot (-\vec{n})]_{plasma} &= j[\vec{j} \cdot \vec{n}] \phi_a - \epsilon \sigma_B T^4 \\
\mu \frac{\partial (\vec{v} \cdot \vec{s})}{\partial \vec{n}} &= \vec{\tau}_a + f_L \frac{\partial \gamma}{\partial T} \frac{\partial T}{\partial \vec{s}} \\
\frac{\partial \gamma}{\partial T} &= -A_r - R_s \Gamma_s \ln(1 + Ka_s) - \frac{Ka_s}{1 + Ka_s} \Gamma_s \frac{\Delta H_o}{T} \\
K(T) &= k_s \exp\left(-\frac{\Delta H_o}{R_s T}\right) \\
\end{aligned}$$

$$\begin{aligned}
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\end{aligned}$$

$$\begin{aligned}
\text{Main boundary conditions} \\
\end{aligned}$$











Results Application to pulsed current welding

80/160 A- 1 Hz α 60°- h 3 mm





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80/160 A- 1 Hz α 60°- h 3 mm

Fully penetrated weld pool



Solutions at t=4.5 s and t=5 s

Free surfaces shape at different times





Experimental validation

Experimental procedure

Observation of the weld pool using an IR camera









Experimenal width of the weld pool

Matlab image processing algorithm



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Experimental validation

Validation





Thank you for your attention,

Any questions ?







• Appendix B Application to pulsed current welding

80/160 A- 1 Hz α 60°- h 3 mm



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