



Modeling Scattering from Rough Poroelastic Surfaces Using COMSOL Multiphysics

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Outline



- Motivation
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- Implementation
- Scattering Strength Calculation
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- Conclusions

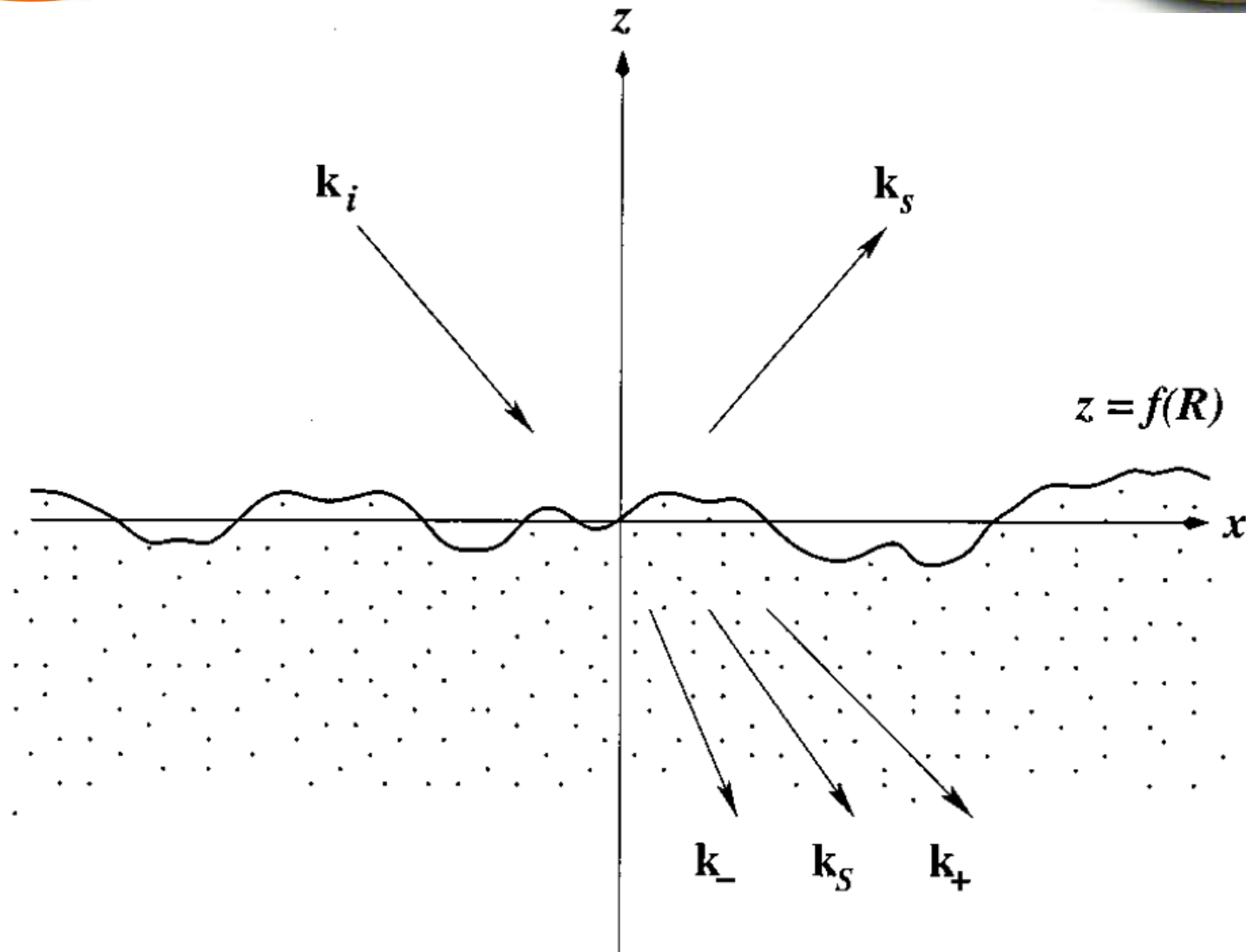


Motivation



- Acoustic scattering from seafloor important source of interference with sonar systems.
- Necessary to accurately model physics of how sound interacts with the sea bottom.
 - Roughness effects
 - Physics of sediment (poroelasticity)

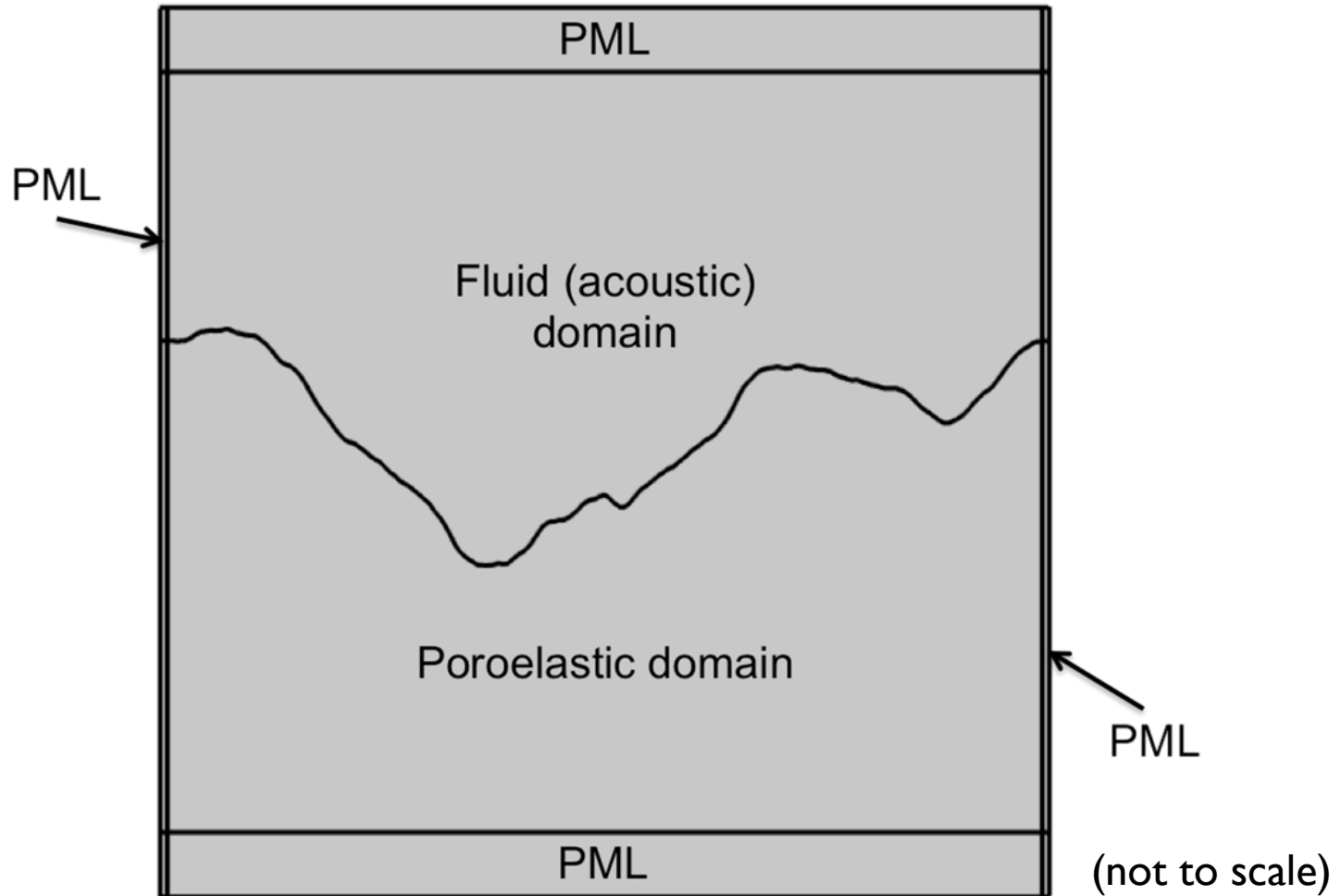
Problem



Reproduced from Yang et al., *IEEE Ocean Eng.*, **27**(3), 2002.



Implementation: Geometry





Implementation: Physics



- Physics assignment
 - Fluid domain modeled with Pressure Acoustics, Frequency Domain Interface.
 - Poroelastic domain modeled with Poroelastic Waves Interface.
- Boundary conditions
 - Continuity of normal stress
 - Continuity of pressure
 - Continuity of normal displacement

} Porous, Pressure Node

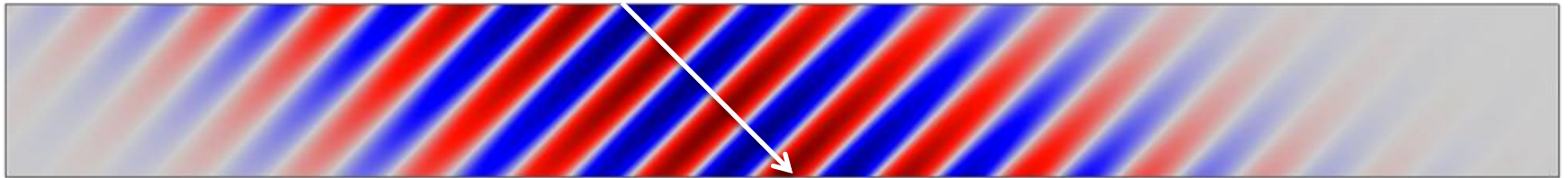
→ Normal Acceleration Node



Implementation: Physics



- Modified Gaussian tapered plane wave used to guard against edge effects.
 - See Thorsos, *J. Acoust. Soc. Am.*, **83**(1), 1988.
 - Implemented as Background Pressure Field.



- Far-Field Calculation node used to find far-field scattered pressure.



Implementation: Mesh



- Rule of thumb: at least 6 elements per smallest wavelength supported by domain.
 - Poroelastic: minimum of slow/shear wavelength.
- Computationally demanding due to disparity between compressional and slow/shear speed.
- Slow and shear waves have high attenuation.
 - Sufficient to mesh finely on interface and based on compressional wave elsewhere.



Scattering Strength Calculation



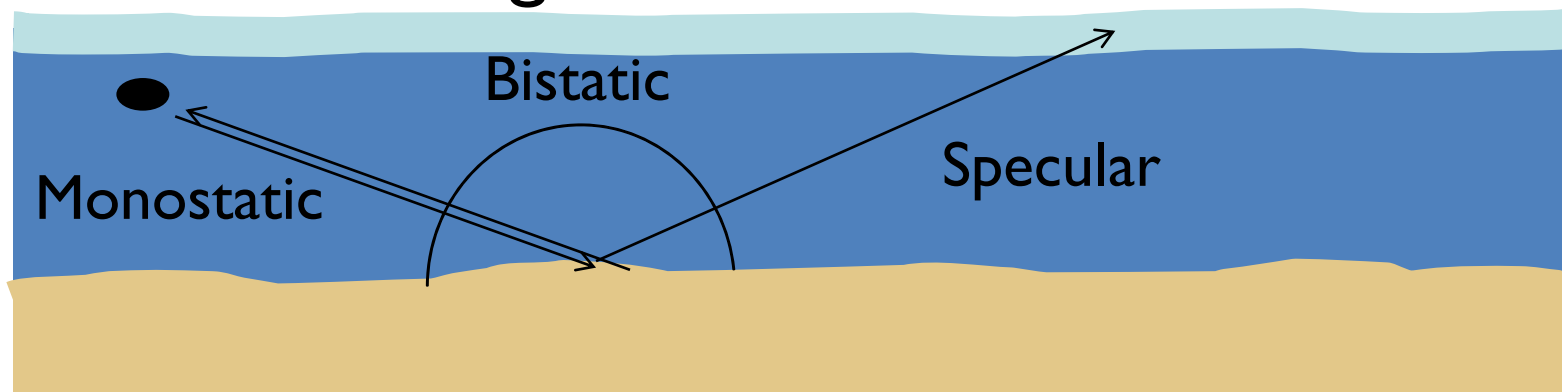
- Many models with unique rough surface realizations run to obtain ensemble average of far-field scattered pressure.
- Average intensity used to calculate scattering cross section.

$$\sigma(\theta, \theta_s) = \frac{\langle I_s \rangle r \sin \theta}{E_f}$$

- Scattering strength: $10 \log_{10} \sigma(\theta, \theta_s)$

Numerical Results

- COMSOL calculations compared with more conventional scattering formulations.
 - Perturbation theory
 - Kirchhoff approximation
 - Small-slope approximation
- Monostatic and bistatic results shown for least and most rough cases studied.



Numerical Results

Roughness
Parameters

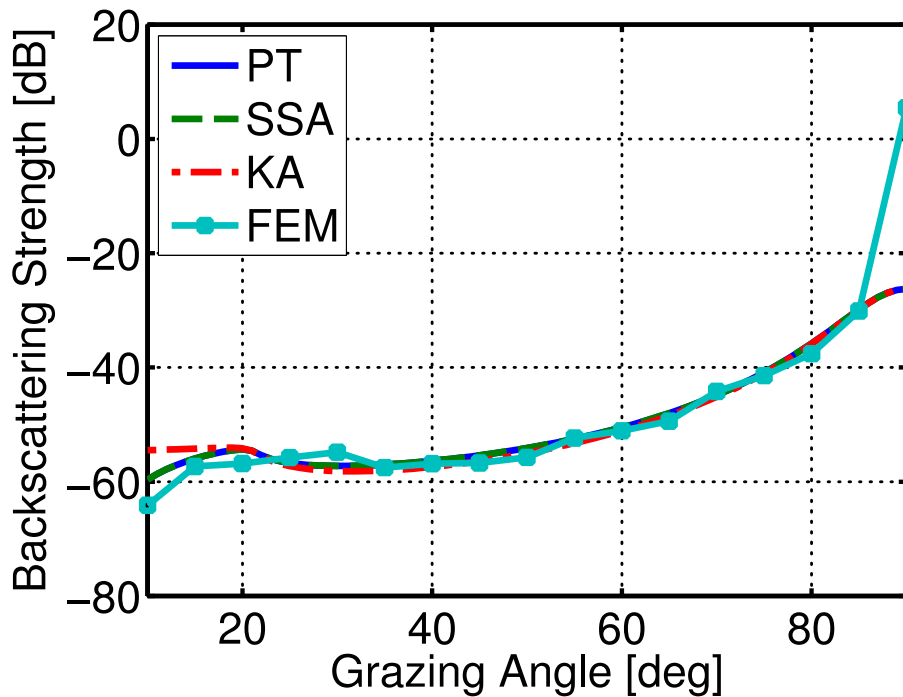
Parameter	Values
Frequency (f)	100 Hz and 3 kHz
<i>rms</i> surface height (h)	0.1 and 1 m
Surface cutoff length (l)	10 m
Bistatic grazing angle (θ)	45 degrees

Material
Properties

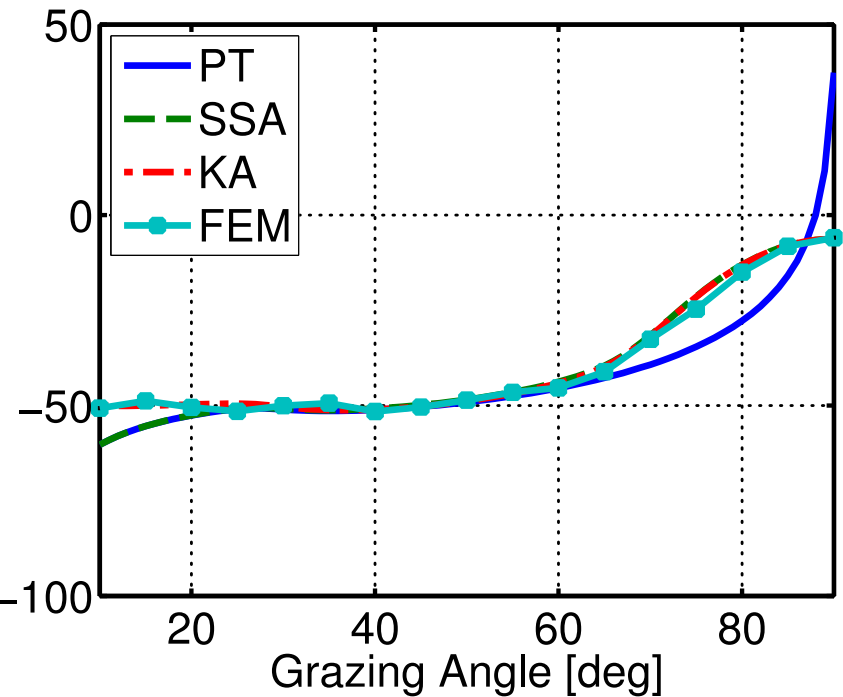
Parameter	Values
Fluid sound speed (c_f)	1530 m/s
Fluid density (ρ_f)	1023 kg/m ³
Fluid compressibility (χ_f)	4.176×10 ⁻¹⁰ Pa ⁻¹
Fluid viscosity (μ_f)	10 ⁻³ Pa·s
Drained density (ρ_d)	1404.5 kg/m ³
Drained bulk modulus (K)	43.6 + i 2.08 MPa
Drained shear modulus (G)	29.2 + i 3.86 MPa
Biot-Willis coefficient (α_B)	0.998 - i 8.15×10 ⁻⁵
Permeability (κ_p)	3×10 ⁻¹¹ m ²
Tortuosity (τ)	1.2
Porosity (ϵ_p)	0.38
Reference frequency (f_c)	410.4 Hz

Results: Monostatic

$f = 100 \text{ Hz}$, $h = 0.1 \text{ m}$, $l = 10 \text{ m}$

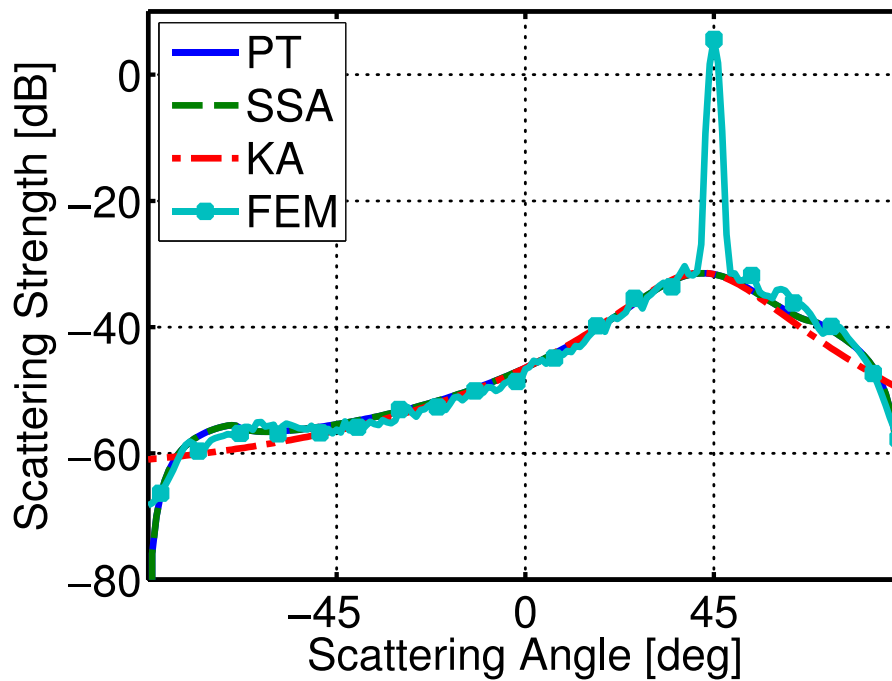


$f = 3000 \text{ Hz}$, $h = 1 \text{ m}$, $l = 10 \text{ m}$

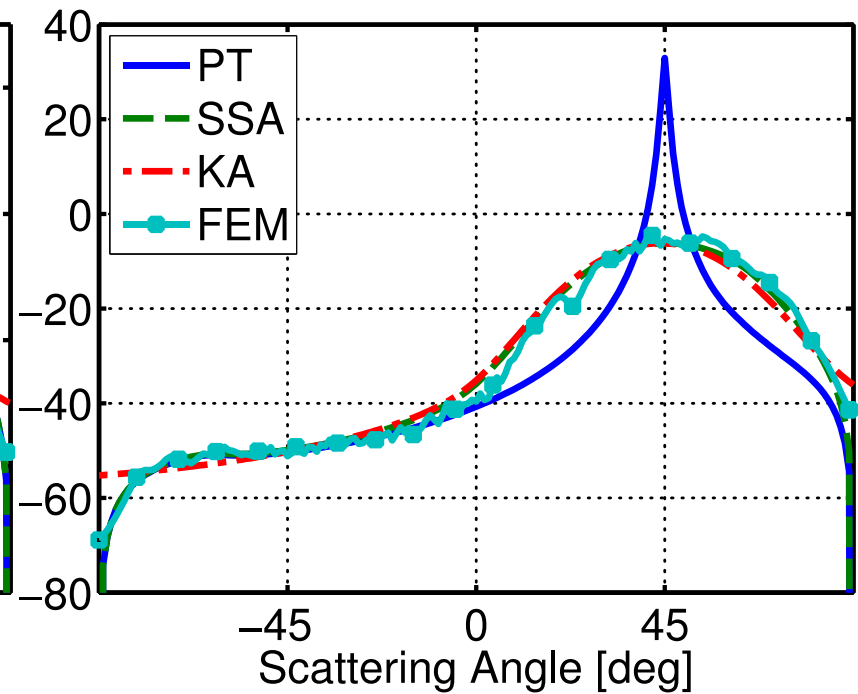


Results: Bistatic

$f = 100 \text{ Hz}, h = 0.1 \text{ m}, l = 10 \text{ m}$



$f = 3000 \text{ Hz}, h = 1 \text{ m}, l = 10 \text{ m}$





Conclusions



- Scattering from rough poroelastic surface successfully modeled using COMSOL Multiphysics.
- COMSOL Multiphysics robust tool for evaluating conventional scattering models.
- Good agreement between FEM and small-slope approximation.
- FEM monostatic results at shallow grazing angles warrant further study.